

Reasoning about Gossip

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- ▶ Gossip protocol

Materials found on <http://reasoningaboutgossip.eu>

Call Condition and Termination Condition

Let us begin slightly vague:

A gossip protocol is a procedure that, until a termination condition is satisfied, selects a call for execution that satisfies a call condition.

Call condition: Assume a set \mathcal{G} of gossip graphs containing G , and a call sequence σ . We recall pair (G, σ) is a **gossip state**.

- ▶ A **call condition** for a call ab is a property P_{ab} that can be determined with respect to gossip state (G, σ) , and that is **epistemic** and **symmetric**. Assume a knows the number of b .
- ▶ **epistemic**: P_{ab} holds for all (H, τ) such that $(H, \tau) \sim_a (G, \sigma)$.
- ▶ **symmetric**: replacing **designated** a, b in P_{ab} by c, d gets P_{cd} .

Termination condition: An agent who knows all secrets is an **expert**. All agents are experts is a **termination condition**. An agent who knows that all agents know all secrets is a **super expert**. All agents are super experts is another termination condition.

Gossip Protocol

Given is a set \mathcal{G} of initial gossip graphs with $G \in \mathcal{G}$ designated. A **gossip protocol** P is a non-deterministic algorithm with G and the empty sequence ϵ as input and a call sequence σ as output. The typical termination condition is that all agents are experts.

Gossip Protocol *While not all agents are experts, choose $a, b \in A$ with $a \neq b$ such that b is a neighbour of a and P_{ab} holds, and execute call ab .*

Protocol-permitted The condition that b is a neighbour of a is not considered part of the protocol condition. A call ab is **possible** if b is a neighbour of a . A call sequence is possible if it consists of possible calls. Given G and σ , possible call ab is P -permitted (protocol-permitted) if P_{ab} holds. A call sequence is P -permitted if all calls in the sequence are P -permitted (ϵ is always P -permitted).

Protocol Extension Given a set \mathcal{G} of gossip graphs and $G \in \mathcal{G}$, the **extension** $P(G)$ of protocol P on G is the set of P -permitted call sequences on G . We write $P(\mathcal{G}) \subseteq P'(\mathcal{G})$ if $P(G) \subseteq P'(G)$ for all $G \in \mathcal{G}$; **$P \subseteq P'$ if $P(\mathcal{G}) \subseteq P'(\mathcal{G})$ for all \mathcal{G} (protocol = extension).**

Different Views on Distributed Gossip Protocols

Gossip Protocol *While not all agents are experts, choose $a, b \in A$ with $a \neq b$ such that b is a neighbour of a and P_{ab} holds, and execute call ab .*

An alternative formulation avoids abnormal termination ('getting stuck'):

While not all agents are experts and there are $a, b \in A$ with $a \neq b$ such that b is a neighbour of a and P_{ab} holds, choose $a, b \in A$ with $a \neq b$ such that b is a neighbour of a and P_{ab} holds, and execute call ab .

If we omit the termination condition we require stabilization:

Choose $a, b \in A$ with $a \neq b$ such that b is a neighbour of a and P_{ab} holds, and execute call ab .

Different Views on Distributed Gossip Protocols

Gossip Protocol *While not all agents are experts, choose $a, b \in A$ with $a \neq b$ such that b is a neighbour of a and P_{ab} holds, and execute call ab .*

The distributed nature of gossip protocol appears as follows:

Each $a \in A$ runs **a-program**: choose $b \in A$ with $a \neq b$ such that b is a neighbour of a and P_{ab} holds, and execute call ab (or else fail). The environment ϵ runs **ϵ -program**: while not all agents are experts, choose $a \in A$ and execute **a-program**.

Again, if we delete 'while not all agents are experts' we require stabilization instead of termination.

Observation Model

Given (arbitrary) observation relations \sim_a and set \mathcal{G} of initial gossip graphs, the **observation model** $\mathcal{M}(\mathcal{G})$ consists of all pairs (G, σ) s.t. $G \in \mathcal{G}$ and σ is possible, and relations $(G, \sigma) \sim_a (H, \tau)$ and $(G, \sigma) \rightarrow (G, \sigma.ab)$ connecting gossip states (we may write \rightarrow_{ab} instead of \rightarrow to denote the executed call). **Special cases:**

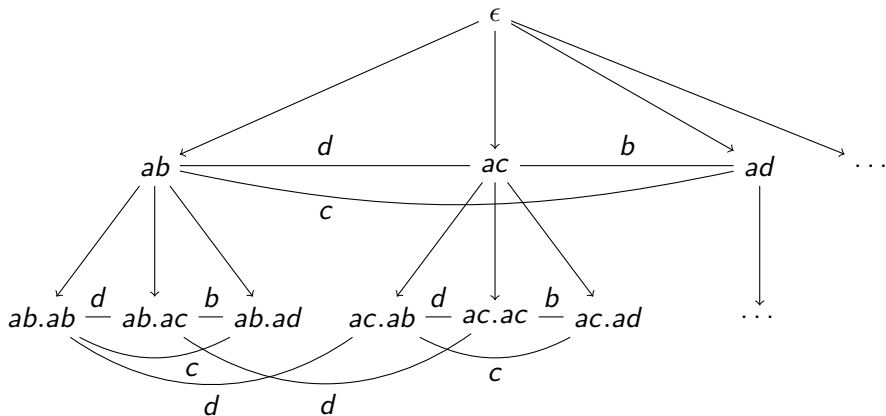
- ▶ $\mathcal{G} = \{G\}$: G is common knowledge among the agents
- ▶ \mathcal{G} is the the set of all lines, all circles, all trees, ...
- ▶ $\mathcal{G} = \{I\}$: the initial secret distribution is common knowledge
- ▶ \mathcal{S} : the set of all sets of initial gossip graphs (\mathcal{I} : all secr. dist.)

$\mathcal{M}_P(\mathcal{G})$ is the restriction of $\mathcal{M}(\mathcal{G})$ to protocol extension $P(\mathcal{G})$. It consists of all gossip states (G, σ) such that σ is P -permitted.

We informally allow infinite call sequences denoted σ^ω . With infinite branch $\epsilon \rightarrow ab \rightarrow ab.cd \rightarrow ab.cd.ef \rightarrow \dots$ in the observation model we associate infinite call sequence $ab.cd.ef \dots$. An infinite call sequence is P -permitted if any (therefore) finite prefix is P -permitted.

Example Observation Model

Partial view of observation model for initial secret distribution ι and agents a, b, c, d . It has **more branches** and has **infinite depth**.



This was synchronous. Asynchronously, $ab \sim_a ab.ab$, $ab \sim_a ab.ac$, ...

Maximal, Fair, Successful, Terminal, Gossip Problem

Given gossip protocol P , set of initial gossip graphs \mathcal{G} , $G \in \mathcal{G}$, and P -permitted call sequence σ (or perm. infinite call sequence σ^ω):

- ▶ σ is **maximal** if for any call ab , $\sigma.ab$ is not permitted.
- ▶ σ^ω is **fair** if for any call ab , if for all i there is $j > i$ such that call ab is P -permitted after $\sigma^\omega|_j$, then for all i there is $j > i$ such that $\sigma^\omega[j] = ab$. (σ^ω is unfair if it is not fair)
- ▶ σ is **successful** if after σ all agents are experts.
- ▶ σ is **terminal** if σ is an execution of protocol P .

Terminal may not be maximal! Further, given gossip protocol P :

- ▶ P is **strongly successful on \mathcal{G}** if for all $G \in \mathcal{G}$, all maximal $\sigma \in P(G)$ and all fair infinite $\sigma^\omega \in \mathcal{M}_P(G)$ are successful.
- ▶ P is **weakly successful on \mathcal{G}** if for all $G \in \mathcal{G}$, there is maximal $\sigma \in P(G)$ or a fair infinite $\sigma^\omega \in \mathcal{M}_P(G)$ that is successful.

Protocol P is wea/str successful if it is wea/str successful on \mathcal{S} (often, \mathcal{I}). The **gossip problem** is whether P is wea/str successful.

Distributed Epistemic Gossip Protocols

ANY _{ab}	=	\top
CMO _{ab}	=	$ab, ba \notin \sigma$
wCMO _{ab}	=	$ab \notin \sigma$
LNS _{ab}	=	$b \notin S_a^\sigma$
PIG _{ab}	=	$\exists \tau \sim_a \sigma, \exists c, c \in S_a^\tau \setminus S_b^\tau \text{ or } c \in S_b^\tau \setminus S_a^\tau$
KIG _{ab}	=	$\forall \tau \sim_a \sigma, \exists c, c \in S_a^\tau \setminus S_b^\tau \text{ or } c \in S_b^\tau \setminus S_a^\tau$
SPI _{ab}	=	spider: if a calls b , a gets the token (if any) from b
TOK _{ab}	=	token: if a calls b , a hands her token to b

ANY	=	any call is permitted
CMO	=	after call ab , a and b may not call each other
wCMO	=	after call ab , a may not call b
LNS	=	a does not know ('hold') the secret of b
PIG	=	a considers possible that a or b will learn a secret
KIG	=	a knows that a or b will learn a secret
SPI	=	token holders may make a call, and then keep their token
TOK	=	token holders may make a call, and then lose their token

Relations between Gossip Protocols

- ▶ LNS, CMO, wCMO only permit finite call sequences.
- ▶ ANY, PIG permit infinite call sequences.
- ▶ ANY permits fair infinite call sequences on \mathcal{I}
- ▶ PIG does not permit fair infinite call sequences on \mathcal{I}
- ▶ LNS = KIG (that is, extensions $\text{LNS} \subseteq \text{KIG}$ and $\text{KIG} \subseteq \text{LNS}$) for asynchronous observation relations
- ▶ all gossip protocols are successful on \mathcal{I} (initial secret distr.)

Lots more to follow in the coming lectures, for synchronous relations, for arbitrary initial gossip graphs, for ... For now, another comparison of protocol extensions:

Gossip Protocol Extension Hierarchy

